

汇交力系的合力投影定理



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设汇交力系 $F_1, F_2 \cdots F_n$ 中任一力 F_i 在直角坐标系 oxy 三个坐标轴上的投影为 X_i, Y_i, Z_i , 沿坐标轴正向的单位矢量为 i, j, k , 则力的解析式为:

$$F_i = X_i i + Y_i j + Z_i k$$



$$F_1 = X_1 i + Y_1 j + Z_1 k$$

$$F_2 = X_2 i + Y_2 j + Z_2 k$$

$$\vdots \quad \quad \quad \vdots$$

$$F_n = X_n i + Y_n j + Z_n k$$



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$$\vdots \quad \quad \quad \vdots$$

$$F_n = X_n i + Y_n j + Z_n k$$



$$R = \sum_{i=1}^n F_i = \left(\sum_{i=1}^n X_i \right) i + \left(\sum_{i=1}^n Y_i \right) j + \left(\sum_{i=1}^n Z_i \right) k$$

$$R = R_x i + R_y j + R_z k$$



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$$\begin{cases} \boldsymbol{R} = \sum_{i=1}^n \boldsymbol{F}_i = \left(\sum_{i=1}^n X_i \right) \boldsymbol{i} + \left(\sum_{i=1}^n Y_i \right) \boldsymbol{j} + \left(\sum_{i=1}^n Z_i \right) \boldsymbol{k} \\ \boldsymbol{R} = \underline{R_x} \boldsymbol{i} + \underline{R_y} \boldsymbol{j} + \underline{R_z} \boldsymbol{k} \end{cases}$$

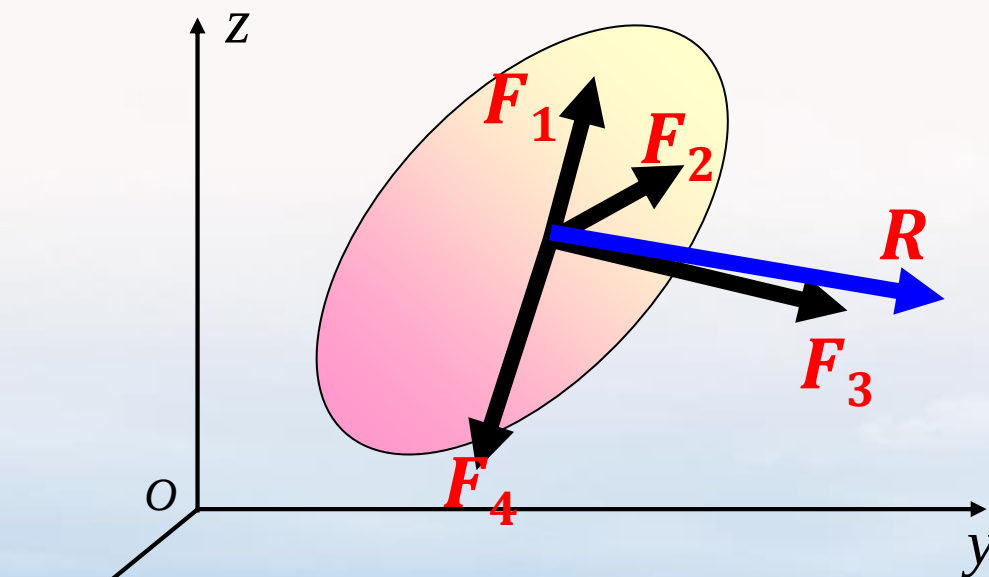
$$\begin{cases} R_x = \sum X \\ R_y = \sum Y \\ R_z = \sum Z \end{cases}$$

汇交力系合力投影定理：合力在任一轴上的投影等于各分力在同一轴上投影的代数和。



汇交力系的合力投影定理

应用汇交力系合力投影定理求汇交力系的合力



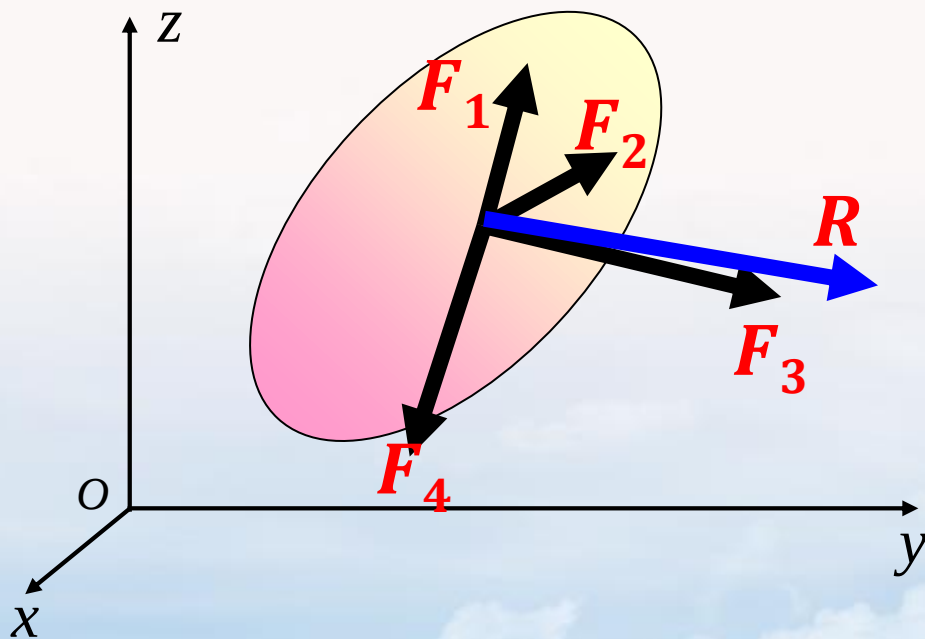
$$\begin{cases} R_x = \sum X \\ R_y = \sum Y \\ R_z = \sum Z \end{cases}$$

$$R \rightarrow \begin{cases} R_x \\ R_y \\ R_z \end{cases} \rightarrow \begin{cases} R = \sqrt{R_x^2 + R_y^2 + R_z^2} \\ \cos(R, i) = \frac{R_x}{R}, \cos(R, j) = \frac{R_y}{R}, \cos(R, k) = \frac{R_z}{R} \end{cases}$$



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应用汇交力系合力投影定理求汇交力系的合力



$$\begin{aligned} \sum X &= R_x \\ \sum Y &= R_y \\ \sum Z &= R_z \end{aligned} \quad \rightarrow \quad \begin{cases} R = \sqrt{R_x^2 + R_y^2 + R_z^2} \\ \cos(R, i) = \frac{R_x}{R}, \cos(R, j) = \frac{R_y}{R}, \cos(R, k) = \frac{R_z}{R} \end{cases}$$

